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Seismic Inversion Based SRV and Reserves Estimation for Shale Plays

Saurabh Sinha, Kurt J. Marfurt, Deepak Devegowda, and Rafael Pires de Lima, University of Oklahoma; Sumit Verma, University of Texas, Permian Basin

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Abstract

Estimation of stimulated rock volume (SRV) is the cornerstone offield development planning in shale reservoirs. The EUR has a first order dependency on the SRV and therefore its estimation is extremely critical for field development.

In this paper, we propose a methodology to estimate the SRV and hence the EUR for a shale reservoir using seismic data, flow and geomechanical simulation. The backbone of our methodology is seismic inversion coupled with geomechanical simulation. We apply our technique to data acquired from the Barnett shale.

In this work, we first use 3D seismic and sonic logs to perform pre-stack seismic inversion. Then, we derive the distribution of Poisson's ratio and Young's modulus in the area of interest (AOI). We constrain the porosity in our geo cellular model using a rock type model. Our rock type model for this work is based on k-means clustering on multi-well log analysis.

We modeled a well in the AOI for which microseismic data is available. Weused a coupledflow and geomechanical simulator to mimic the fracturing process and the fluid volumes injected during the actual completion of the well. For geomechanical coupling, we used Barton-Bandis model in seismic inversion-derived Young's modulus and Poisson's ratio 3D volumes. Next, we compare our results with the SRV obtained by an analysis of microseismic data. We reconcile differences in the model-derived SRV and then calibrate the resulting flow model and use the history-matched model for forecasting production.

Our results indicate an excellent match on SRV and therefore production data. Because we usevariable geomechanical parameters along the lateral, we observe irregular SRV's and drainage areas consistent with the microseismic data. Our methodology for predicting microseismic can be used for asset evaluation, acreage prioritization and to optimize the completion design in unconventional plays.

Introduction

Figure 1a shows the EUR plotted against the SRV derived from a dual-porosity reservoir simulation model for a shale well completed in a naturally fractured shale reservoir such as the Barnett shale. The reservoir model is specified to be 7000 ft. deep with a median porosity of 14% and a permeability of 1000 nD. Assuming that no other variables change, the EUR increases with the SRV. In reality, this linear trend may

not necessarily be true because of other factors such as improper proppant placement and geomechanical effects over time. However, the model does illustrate the significance of the SRV to enhance the EUR/well.



Figure 1—a) Model-predicted EUR versus SRV. The EUR strongly depends on the SRV. The model is shown in Figure 1b. b) Complex fracture network in the model and enhanced permeability zones.

Production forecasting and estimation of reserves is the key challenge in unconventional field development. 3D seismic surveys provide high value in understanding the reservoir and helps operators to:

- a. Identify and develop high value acreageand prioritize which part of the acreage be developed first.
- b. Optimize completion design for wells: Knowing SRV's ahead of time, critical changes can be made in areawise completion design to maximize recovery from the well. For example, for wells in different sections of the play associated with different fluid types.
- c. Optimize the well spacing: If the extent of SRV is known along with the geometry, optimal well spacing can be implemented in field to minimize well interference and maximize recovery factors.
- d. Accurate reserves reporting in underdeveloped portions in the reservoir.

The information derived from 3D seismicanalysis may help operators achieve the above-mentioned objectives prior to drilling. Moreover seismic derived properties are available at a much finer interval than well spacing. Although, the resolution depends on the acquisition geometry, well control is likely not available at such finer intervals.

Previous attempts of correlating production with 3D seismic do not include the direct coupling of physical properties with constitutive equations. For example, Zhang et al. (2015) elaborated the use of pre-stack inversion and Rickman's equation (Rickman et al., 2008)to estimate Poisson's ratio, Young modulus and brittleness. Perez Altamar and Marfurt (2015) utilized the same concept and added lambda-rho and mu-rho

to better identify the brittle and ductile areas. Verma et al. (2016) further extended the concept of brittleness and added total organic carbon (TOC) from Passey's method to identify the sweet spots in Barnett shale.

Unfortunately, all the previous methods, while promising, do not use any physical law coupling with fluid flow. This leads to qualitative correlation with cumulative produced volumes or EUR's that do not provide any quantitative relationships. Consequently, sensitivity analyses to different well designs, fracture designs and spacing is challenging.

Reservoir engineers rely on the use of decline curve analysis, analytical methods and reservoir simulation to estimate EUR's. Lee and Sidle (2010) discuss the methods of decline curve analysis while Stalgorova and Mattar (2013) document some of the analytical methods. Coupling of flow simulations with geomechanics is discussed in detail by Ji and Sullivan (2009). Amongst these methods, reservoir simulation is the most rigorous and provides the capability to perform sensitivity analyses as well as the testing different rock failure criterion.

Methodology

Development of geological model

We use a 3D seismic survey from Barnett shale as shown in Figure 2 highlighting the areal extent of the survey and the well control available from pilot wells in the area. The survey consists of 366 inlinesand 270 crosslines separated by an interval of 110 ft. in both cases. The total survey is thus 7.6 miles by 5.6 miles. The survey has 27 wells with well logs. The location of these wells is shown in Figure 2 along with the picked Viola Limestone surface indepth domain. The sampling rate used in the survey is 2 ms.



Figure 2—Areal extent of the seismic survey and the available wells. The survey is 7.6 miles by 5.6 miles and consists of 366 inlines and 270 crosslines. The survey has good well control with 27 pilot wells in the area. The horizon overlay with the inlines and crosslines is the top of Viola limestone after depth conversion.

The formation of interest is lower Barnett because most of the wells are completed in this zone. The lower Barnett is relatively flat in our area of interest (AOI) with minimum to no fault planes. First, we pick the seismic horizons in time domain and then convert them into depth domain using a linear velocity model. The Lower Barnett in our area has a thickness of 300- 350 ft.

Figure 3 shows an example stratigraphic cross section from the wells in our area. The stratigraphic cross section consists of Viola Limestone, Lower Barnett, Forestburg limestone and Upper Barnett. The Forestburg limestone is squeezed between lower and upper Barnett and thins out towards the SE section in the area (Verma et al. 2016)).



Figure 3—Stratigraphic cross section in the area. Forestburg limestone is sandwiched between upper and lower Barnett. Most wells are completed in lower Barnett in this area. The lower Barnett thickness varies from ~ 300 - 350 Ft. in this area. Horizon 1 (H1) is the top of upper Barnett, H2 is the top of Forestburg limestone, H3 is the top of lower Barnett and H4 is the top of Viola limestone.

We used the pre-stack inversion to derive Young's modulus (λ) and Poisson's ratio (μ) (Zhang et al. 2015). The results of Poisson's ratio and Young's modulus along with seismic amplitude is shown in Figure 4. It can be observed from Figure 4 that the range of Young's modulus in our AOI varies between 60-70 GPa and Poisson's ratio varies between 0.23-0.30. These values are variable with depth and agree with those reported by Vermylen (2011) and Sone (2012) from laboratory measurements.





Rock-Type Model

For rock typing we used k-means clustering based on the gamma ray, sonic and bulk density log. We identify a total of 6 rock types in the upper and 6 rock types in the lower Barnett. Figure 5a shows the "elbow-point" plot which allowed us to determine the number of clusters by defining the sum of squares between each cluster. The change in the slope starts around 4 clusters, but the ideal number may be anywhere between 4 and 8 clusters. Figure 5b shows the clustersplotted with the first two principal components.

We calculate these rock types in every well and derived the variograms for the facies model. We then use sequential indicator simulation (SIS) to distribute these facies in the reservoir. Figure 6 show the distribution of these rock types at top of the lower Barnett. We then use these rock types to constrain the density porosity derived from these wells. We use sequential gaussian simulation (SGS) to populate rock type constrained porosity. Figure 6 shows the facies and Figure 7 shows the porosity cross section at the top of lower Barnett.





Figure 5-a) Number of clusters from k-meansb) Cluster plot using principal components



Figure 6—a) Rock type model at the top of lower Barnett. Rock types are based on k- means clustering of well log data from bulk density, sonic and gamma ray logs. b) shows the histogram of porosity for different facies and their respective percentages in lower Barnett. The histogram shows good correlation between the log-derived values of porosity and the upscaled cell values.



Figure 7—Rock type constrained porosity in lower Barnett shale and distribution of porosity within Barnett Shale. The porosity varies from 3% to 27% in lower Barnett with a median porosity of 16%.

Completion Details and In-Situ Stress

The well in the model has ~ 2000 ft. lateral length (perforated and completed) with 100 ft stage spacing and is completed with 20 stages. The design pumping rate is 64 BPM cluster. Microseismic is recorded in the well with an observation well to the south-east of it. The well is a single well completion with just one well on the PAD and without zipper fracturing.

To calculate the pore pressure, we used mud weight gravity in the region where there is no lost circulation or gas influx. We calculated pore pressure gradient in our area as 0.475 psi/ft which corresponds to the value of 0.48 psi/ft reported by Vermylen (2011). To calculate the vertical stress, we integrate the bulk density log. We do not have formation image logs or formation fracturing tests to calculate the maximum (S_{hmax}) and minimum (S_{hmin}) horizontal stresses and orientation.

Therefore we choose the first fracturing stage shut in pressure to initialize S_{hmin} . Due to excessive friction losses such as proppant and gel viscous flow as well as dynamic stress changes we avoid the use of other stages to calculate S_{hmin} . We show this pressure in Figure 8.



Figure 8—Fracturing report of the well in which microseismic is obtained and is modeled in this study. It can be observed that the ISIP for the first stage is ~3600-3700 Psi and hence is used as S_{hmin.} (Image modified from that provided by the operator).

The Barnett has been reported as being characterized by relatively low stress anisotropy (Vermylen, 2011) and therefore we assume S_{hmin} to be slightly lesser (by 100 psi) than S_{hmax} . Table 1 summarizes these values.

To propagate the fractures in the model, we use the Barton-Bandis model (Bandis et al. 1983) with a dual porosity assumption. The numerical groundwork for implementing the methodology is described by Nghiem et al. (2004). Figure 9 shows the conceptual background for the model. As injection continues, pore pressure increases and hence effective normal stress decreases. At the effective opening stress for the natural fractures, the fractures open and are characterized by a high fracture conductivity. The permeability declines as the effective stress increases again during production due to a decrease in pore pressure.



Figure 9—Modified Barton- Bandis model used in this study. The image is modified after Sinha et al. (2017) (original image modified from Tran et al. (2009)). As the injection continues the effective normal stress (overburden stress – pore pressure) decreases and at point of rock failure there is a sudden increase in permeability. After injection stops, the permeability decreases semi-logarithmically and stabilizes at a residual permeability of fractures. We have used this residual permeability as a history matching parameter for the long-term production behavior

We use the fracturing schedule shown in Figure 8 to inject the fracturing water from toe towards heel in 20 stages. As the fracture opening stress is reached, the fractures retain some portion of the initial high permeability value following an initial period of production. The enhanced permeability then follows a semi-logarithmic decline and the fracture eventually retains a minimum permeability that explains the long-term production behavior (The permeability model is shown in Figure 9). We have assumed an isotropic horizontal reservoir matrix permeability before fracturing.

Parameter	Value
Initial fracture aperture	0.01 Ft.
Initial fracture stiffness	2.52 E+06
Initial fracture opening stress (limiting case)	3000 Psi
Initial hydraulic fracture permeability	25000 mD
Fracture closure permeability	20000 mD
Initial fracture permeability, after initial production	15000 mD
Biot's coefficient	0.8
Maximum (S _{hmax})and minimum effective stresses (S _{hmin})	3700 Psi and 3600 Psi
Vertical effective stress	4340 Psi

Table 1—Parameters used for stress initialization

History Matching

The well is completed in the dry gas window of the Barnett hence, our model is assumed to contain only single-phase methane for the fluid model. We use the residual permeability in Barton-Bandis model as the history matching parameter to match the gas volumes. We do not have daily production for the wells and therefore used public information from the website Drillinginfo®, for the monthly allocated production for this well.

We operate the well on gas cumulative control until production history is available. The pressures are not available for this well on Drillinginfo®. We therefore used the occasional production tests that report the static tubing head pressures (THP) on these wells to calibrate the BHP using the gas gravity and the Beggs and Brill correlation (Beggs and Brill, 1973). After the actual production history, we operate the well on BHP constraintobtained at the last day of reported production. Figure 10a shows results of gas flow rates obtained from the simulation as well as the simulation-derived EUR which is comparable to the EUR obtained from a modified hyperbolic decline curve (Lee and Sidle, 2010) with a b- factor greater than 1 and a terminal decline of 5%.



Figure 10—a) shows the results of the decline curve analysis(DCA) and the reserves from DCA for the test well. b) shows the simulation results from the test well. The results appear to be stepwise in simulation results due to monthly production. As the well is running on gas cumulative control, there is only one curve visible for gas production i.e. exact match on gas rates. The EUR calculated is 1.85 BSCF from simulation for a well life of 20 years. From DCA, the EUR calculated is 2.1 BSCF and are in the same ballpark.

Calibration Results

We derived an SRV using a coupled geomechanical-flow model with seismic-derived Poisson's ratio and Young's modulus to model the fracturing procedure. We modeled the SRV as a function of formation storage capacity, permeability, stress initialization and geomechanical parameters like Poisson's ratio and Young's modulus. The results indicate the presence of an irregular SRV with non-uniform stimulation along the wellbore. Our forward modeling approach to predict the SRV from seismic-derived properties shows excellent correspondence with the microseismic-derived event locations as shown in the top (plan view)

and bottom (cross-sectional view) panels of Figure 11. Figure 11a shows the enhanced permeability regions surrounding the wellbore that is predicted from the forward modeling approach showing good correlation with the microseismic event locations in Figure 11b. Figures 11c and 11d show the same with in a cross-sectional view. The grid boundary is shown in Figure 11a in a maroon square box. The fracture growth is upwards with more stimulation in the heels and less towards the toe side of the lateral as seen in Figure 11c. There is more stimulation on one side of the lateral than the other due to irregular failure criterion (Young's modulus and Poisson's ratio maps). We also see highly conductive fractures in the middle portion of the reservoir which is reflected in microseismic events density (Figure 11d).



Figure 11—a) Permeability mapafter the stimulation b) Top view of the actual stimulation treatment microseismic (image provided by the operator) c) I-K view of the stimulation d) I-K view of the actual stimulation microseismic (image provided by the operator). Figure (a) show a high area of permeability away from the wellbore which cannot be predicted without a spatial gradation in geomechanical and petrophysical properties. Figure (a) also show the boundary of the finite element geomechanical grid causing some of the boundary effects. There is a zone of no stimulation in the middle of the lateral which is not reflected in actual seismic and could be due to some natural fractures or grid sizing. Figure (c) show more conductive SRV at the middle of the lateral and diminishing conductivity away from the wellbore. Figure (d) show higher microseismic density in the middle section of the lateral and microseismic event density fading away from the wellbore consistent to the observation in Figure (c).

The initial production is matched by tuning the initialvalue of fracture conductivity and the longer term production is matched by calibrating the gradual logarithmic declining fracture conductivity in the Barton-

Bandis model. We observe a general trend of permeability diminishing away from the wellbore but also many regions of high permeability away from the wellbore. This observation differs from the general assumption thatfracture permeability diminishesaway from the wellbore. Our results show that during production the drainage volumes may encompass regions of high permeability instead of progressively moving towards lower permeability regions and thisshould be reflected in the flowing material balance plots suggested by Suliman et al. (2013) and Samandarli et al. (2011).

These high permeability areas can also explain the gradual flattening of decline (as seen in Figure 10a) and b-factors for DCA in some wells contrary to what is expected because the well continues to drain higher permeability regions at a later period.

Conclusions

The methodology presented in our paper presents a promising approach to utilize 3D seismic data, microseismic analyses and well-log-derived 3D property models to match production history and predict EUR. The procedure is summarized below:

- 1. Comparison of microseismic-derived SRV on to SRV predicted from a seismic-derived 3D model of Young's Modulus and Poisson's ratio.
- 2. Utilize the calibrated SRV model in a coupled geomechanical-flow model to match production history by adjusting fracture conductivities.

The advantage of our approach is that the SRV can be predicted with a high degree of confidence prior to fracturing using 3D seismic data. Although the SRV can be inferred solely from microseismic data as shown by Sinha (2017) and Suliman et al. (2013), our approach allows us to predict the anticipated SRV prior to drilling or fracturing thereby providing better controls on the EUR.

In our study, we observed SRV consistent with microseismic data and hence we are able to forecast EUR reliably. We can also quantitatively infer high permeability enhanced fracturing zones and provide a viable way to correlate microseismic event density with the permeability.

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Nomenclature

- EUR -Expected ultimate recovery
- SRV Stimulated Rock Volume
- S_{hmax} Maximum horizontal stress
- S_{hmin} Minimum horizontal stress
- DCA Decline curve analysis
- FBHP Flowing bottomhole pressure

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