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Multispectral, multiazimuth and multioffset coherence attribute applications

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Abstract

The coherence attribute computation is typically carried out as a poststack application on 3D prestack migrated seismic data volumes. However, since its inception, interpreters have applied coherence to bandpass-filtered data, azimuthally-limited stacks, and offset-limited stacks to enhance discontinuities seen at specific frequencies, azimuths, and offsets. The limitation of this approach is the multiplicity of coherence volumes. Of the various coherence algorithms that have evolved over the last twenty-five years, the energy ratio coherence computation stands apart from the others, being more sensitive to the seismic waveform changes rather than changes in their amplitude. The energy ratio algorithm is based on crosscorrelation of five or more adjacent traces to form a symmetric covariance matrix that can then be decomposed into eigenvalues and eigenvectors. The first eigenvector represents a vertically variable, laterally consistent pattern that best represents the data in the analysis window. The first eigenvalue represents the energy of the data represented by this pattern. Coherence is then defined as the ratio of the energy represented by the first eigenvalue to the sum of the energy of the original data. An early generalization of this algorithm was to compute the sum of two covariance matrices, one from the original data and the other from the 90° phase rotated data, thereby eliminating artifacts about low amplitude zero-crossings. More recently, this concept has been further generalized by
computing a sum of covariance matrices of traces represented by multiple spectral components, by their azimuthally-limited stacks, and by their offset-limited stacks. These more recently developed algorithms capture many of the benefits of discontinuities seen at specific frequencies, azimuths, and offsets but present the interpreter with a single volume. We compare the results of multispectral, multiazimuth and multioffset coherence volumes with the traditional coherence computation, and find that these newer coherence computation procedures produce superior results.

Introduction

Coherence is a discontinuity detection attribute, which is applied to stacked migrated seismic data volumes to facilitate the interpretation of geologic structural or stratigraphic discontinuities. In general, coherence is applied to data stacked after migration, and is available in most workstation interpretation software packages. Various implementations of coherence algorithms have evolved over the last 25 years including crosscorrelation-based (Bahorich and Farmer, 1995), semblance-based (Marfurt et al., 1998), variance-based (Pepper and Bejarano, 2005), Sobel filter based (Luo et al., 1996, 2003), eigenstructure-based (Gersztenkorn and Marfurt, 1999), and gradient structure tensor-based (Bakker, 2003) algorithms. The algorithms most commonly available on workstation software packages are the semblance and some form of eigenstructure decomposition of covariance matrices. We restrict our analysis to the application of the energy-ratio algorithm (Chopra and Marfurt, 2008), which is a variation of the eigenstructure approach. We discussed in detail the applications of coherence attribute to seismic data in Chopra and Marfurt, (2007, 2018a, 2018b).
The interpretation of stratigraphic features on seismic data is dependent on their bandwidth. In general, seismic data that have a higher bandwidth also provide greater lateral resolution, resulting in sharper coherence images. However, because of tuning, some frequencies may be more sensitive to a given lateral stratigraphic discontinuity than others. Likewise, a given seismic wavelet may show two different horizons to be “aligned” across a fault (e.g. Libak et al., 2017) while a wavelet at a different frequency may be misaligned. For these reasons, sometimes interpreters run spectral decomposition (Partyka et al., 1999) or compute spectral voice components prior to computing coherence (Chopra and Marfurt, 2016). In general, higher frequency spectral magnitudes or voice components highlight lateral variation in thinner beds while lower frequency magnitude or voice components highlight lateral changes in thicker beds.

Another tool at their disposal is the red-green-blue (RGB) blending of three frequency components, which allows the interpreters to corender the information content at different scales. While useful, this color display tool has a limitation in that it can show only three components at a time (Henderson et al., 2008).

Obviously, if a given spectral component highlights a feature of interest, one can delineate edges in such volumes using coherence. The same argument applies to azimuthally limited, offset-limited, or angle-limited partial stacks of the migrated data. Because of AVO effects, lithologic “edges” may be stronger on coherence computed on the far-offset stack. Similarly, faults and other discontinuities will be better illuminated by a perpendicular rather than a parallel azimuthally-limited partial stack (Chopra and Marfurt, 2007). Unfortunately, there are two major drawbacks to this “component analysis” workflow. First, each spectral component or partial stack has a lower signal-to-noise content than the broadband or full stack data volume. Second, the
interpreter is now faced with interpreting multiple coherence images, one for each component, which (because of their lower signal-to-noise ratio) can be both tedious and very time-consuming.

Marfurt (2017) describes a way to construct a multispectral covariance matrix by summing the covariance matrices for all the input spectral components each of which is oriented along structural dip using analytic voice components. The energy ratio coherence computed using this approach is referred to as multispectral coherence. Qi et al. (2017) extended this concept to azimuthally-limited and offset-limited partial stacks, resulting in “multiazimuth” and “multioffset” coherence.

Recall that the seismic response across offsets is sensitive to changes in lithology, porosity and fluid content. We, therefore, expect that the attribute images generated from offset-limited volumes will show some sensitivity to these changes. In fact, the stratigraphic effects have the maximum influence on the near-offset range, and the lithology and fluid have the greatest effect on the longer offsets. When the seismic amplitudes are stacked over all offsets, we obtain some average of all these responses.

While the presence of hydrocarbons can cause changes in seismic response with offset or incident angle, aligned vertical faults and fractures cause azimuthal variations in the seismic amplitude, phase and velocity (Grimm et al., 1999; Lynn, 2018a, 2018b). The routine production processing typically stacks all azimuths and thus obliterates the azimuthal variation of moveout and amplitude.
In this paper, we examine the interpretational value of these recent developments. First, does coherence computed from band-limited, offset-limited, or azimuth-limited stacked seismic volumes, contain information that is in some way greater than that of the broadband or stacked image? Second, do multispectral, multiazimuth, or multioffset images capture any of this lost information?

**Multispectral coherence**

The energy ratio coherence algorithm has been described in detail, along with applications, by Chopra and Marfurt (2007, 2018a). We briefly mention some of the salient details that would lead us to the applications we describe in this paper.

In the energy ratio algorithm, the covariance matrix is computed from the analytic trace composed of the seismic data, \( d \), and its Hilbert transform, \( d^H \), along the structural dip, to prevent “structural leakage,” corresponding to zero crossings (Chopra and Marfurt, 2007). We define the covariance matrix \( C \) for \( M \) traces within a \( \pm K \) sample window:

\[
C_{mn} = \sum_{k=-K}^{K} \left[ d(t_k, x_m, y_m)d(t_k, x_n, y_n) + d^H(t_k, x_m, y_m)d^H(t_k, x_n, y_n) \right],
\]

where \( t_k \) is the time of a structurally interpolated sample at a distance \( (x_m, y_m) \) about the analysis point at \( (x=0, y=0, t=0) \). The \( C_{mn} \) component of the covariance matrix is simply the crosscorrelation of trace \( m \) with trace \( n \) over \( 2K+1 \) samples. The value of \( M \) typically ranges from 5 (for higher resolution in good data) to 13 (for lower resolution in noisier data). The value of \( K \) ranges from 2 for good quality data (and in order to avoid mixing stratigraphy) to no more than \( K = T_{\text{min}}/(2\Delta t) \) where \( T_{\text{min}} \) is the shortest usable period, and \( \Delta t \) the sample interval.
Most of the covariance matrices we encounter in attribute analysis are symmetric and are decomposed as

$$ \mathbf{C} \mathbf{v}^j = \lambda_j \mathbf{v}^j, $$

(2)

where \( \mathbf{C} \) is an \( M \) by \( M \) square covariance matrix, \( \lambda_j \) is the \( j \)th of \( M \) eigenvalues, and \( \mathbf{v}^j \) is the corresponding eigenvector. Because the matrix is symmetric, the eigenvalues are all non-negative.

The energy ratio coherence computation is given as:

$$ C_{\text{Energy ratio}} = \frac{\sum_{k=-K}^{K} \sum_{m=1}^{M} \left[ \left| d_{PC}(t_k, x_m, y_m) \right|^2 + \left| d_{HC}(t_k, x_m, y_m) \right|^2 \right]}{\sum_{k=-K}^{K} \sum_{m=1}^{M} \left[ \left| d(t_k, x_m, y_m) \right|^2 + \left| d^H(t_k, x_m, y_m) \right|^2 \right]}.$$

(3)

In the above mathematical expression, the numerator can be interpreted as the energy of the weighted principal component filtered analytic traces, and the denominator as the sum of the energy of the analytic traces or total energy. In simple notation, the energy ratio coherence may be given as:

$$ C_{\text{Energy ratio}} = \frac{E_{\text{coh}}}{E_{\text{tot}}}.$$

(4)

Dewett and Hensa (2016) first showed the application of multispectral coherence using both amplitude and phase information from different frequency bands of the input seismic data. Thereafter, Marfurt (2017) constructed a multispectral covariance matrix oriented along
structural dip using the analytic voice components (equation 1), and therefore twice as many sample vectors (i.e., spectral voices and their Hilbert transforms):

\[
C_{mn} = \sum_{l=1}^{L} \sum_{k=-K}^{K} \left[ u(t_k, f_l, x_m, y_m)u(t_k, f_l, x_n, y_n) + u^H(t_k, f_l, x_m, y_m)u^H(t_k, f_l, x_n, y_n) \right]. \quad (5)
\]

The corresponding energy ratio coherence computed using this equation is then referred to as \textit{multispectral coherence}.

\textbf{Multiazimuth coherence}

Similar to multispectral coherence procedure, Qi et al. (2017) generate energy ratio coherence by summing \( R \) covariance matrices \( C(\varphi_r) \) computed from each of the \( R \) azimuthally-limited data volumes.

\[
C_{\text{multi-} \varphi} = \sum_{r=1}^{R} C(\varphi_r). \quad (6)
\]

The covariance matrix obtained by summation has the same size as the original single-azimuth covariance matrix, but now has \( R \) times as many sample vectors. The “multiazimuth coherence” is computed from \( C_{\text{multi-} \varphi} \) using equations 2 and 3.

\textbf{Multioffset/multiangle coherence}

Multioffset coherence is computed in an analogous manner to multiazimuth coherence. Instead of the azimuthally-sectored input volumes, one could use the different offset-limited or angle-limited volumes as the input.

\textbf{Why the two operations are different}
Simple analysis will show that computing $R M$-by-$M$ covariance matrices and then summing the results is computationally more expensive than summing the $R$ components and computing a single $M$-by-$M$ covariance matrix. However, because the covariance matrix consists of nonlinear auto and crosscorrelations, these two operations are not equivalent. Let’s use a multiazimuth example as an illustration. Because our velocities are never perfect, the full azimuth stack may be blurred, reducing the coherence anomaly of a small N-S trending fault. In contrast, the E-W azimuthally limited stack will illuminate this fault well. The covariance matrix then captures the discontinuity through crosscorrelation. Other azimuths may exhibit this discontinuity somewhat less, and possibly shifted vertically or laterally. Stacking the covariance matrix combines the discontinuities, some constructively, some destructively. Those that persist across multiple azimuths persist. Finally, in our implementation, the magnitude of the individual covariance matrices is proportional to the energy of the components at that spectral, azimuthal, or offset component, thereby weighting the discontinuity by a level of confidence.

**Applications**

The applications of the three forms of coherence computation discussed above as applied to different data volumes are discussed below.

*Multispectral coherence*

Figure 1 shows a segment of a section from a 3D seismic data volume from the Montney-Dawson area of northeast British Columbia, Canada. Two horizons have been picked on the seismic data and used for generation of the stratal slices shown in Figure 2. This data volume was first used to generate the conventional poststack coherence volume. As the bandwidth of the seismic data
was 10 to 80 Hz, the voice components from 20 Hz to 75 Hz were generated at increments of 5 Hz. These voice components were then used to generate the multispectral coherence. A comparison of the stratal slices 36 ms above the yellow horizon (shown in Figure 1) from the conventional coherence and the multispectral coherence volumes is depicted in Figure 2a and b. The definition of the faults marked with yellow arrows and green arrows are well-defined on the multispectral coherence display. Similarly, the lineaments indicated with blue arrows are not seen on the conventional coherence display but appear on the multispectral display. Some of the features seen on the conventional coherence display marked by magenta arrows or enclosed within magenta and blue ellipses, disappear on the multispectral coherence. Similarly, the divergence of the fault lineaments indicated by the magenta and green arrows on conventional coherence is not noticed on the multispectral coherence display. We recommend the use of both the multispectral and conventional energy ratio coherence so that all the lineament detail can be interpreted on such displays.

Another comparison between the stratal slices generated along the yellow horizon from the same two coherence volumes is shown in Figure 2c and d. In this case since the stratal slice is along a prominent horizon, the trace to trace similarity is high, and hence the display shows mostly high coherence values. But even so, the faint lineaments on conventional coherence display (yellow, blue and green arrows) are defined clearly on the multispectral coherence display.

Typically, the vertical and spatial resolution increase as the voice component frequency increases. It may therefore be expected that coherence generated from voice components at higher frequencies would show higher spatial resolution. To explore this in the present case, in
addition to generating multispectral coherence from voice components ranging from 20 to 75 Hz at 5 Hz increments, another multispectral coherence volume was generated by using frequencies from 50 to 75 Hz at 5 Hz increments. Figure 3 compares the results of these two computations with the conventional “broadband” coherence volume. Notice that the stratal slice from multispectral coherence volume using twelve voice component frequencies shows the best display in that the definitions of the almost-vertical faults (yellow, blue and green arrows) stand out the best. Similarly, the paleochannels going almost east-west (magenta arrows) stand out clearly on this display. The multispectral coherence display in Figure 3c misses out on the definition of some of the feature lineaments that are seen clearly in Figure 3b.

Figure 4 shows a segment of a seismic section from the Montney-Dawson area of north-east British Columbia in Canada. Twenty stratal slices have been generated between two prominent horizons picked on the seismic data and displayed in black. Yellow arrows indicate stratal slices 8, 12 and 14 displayed in Figure 5a-c through the conventional coherence volume (left column) and multispectral coherence volume (right column). Notice the much better definition of the channel features seen on the multispectral coherence displays.

Figure 6 shows a similar comparison between horizon slices from the conventional coherence (left column), and multispectral coherence (right column). The horizon slices in Figure 6a are generated along a horizon picked on the seismic volume at approximately 1200 ms, while those in Figure 6b generated 68 ms deeper. Again, the lineaments are more focused, continuous and thus more interpretable on the multispectral coherence slices in Figure 6b.

_Multiazimuth coherence_
A segment of an inline seismic section from the STACK trend in Oklahoma is shown in Figure 7. Inlines run N-S on the seismic survey and are indicated in Figures 8 – 11.

Figure 8a-f shows six stratal slices from the azimuthally-limited (30° increments) seismic data volumes. The stratal slices have been generated at a level 12 ms above a horizon at 1950 ms on the seismic data. The 288 fold wide-azimuth seismic data are from the STACK trend in Oklahoma, US. The key steps in the processing included azimuthally-compliant pre-migration noise attenuation, 5D interpolation to a set of regularly sampled azimuthal spokes, azimuthal velocity analysis, and spoke-by-spoke post migration noise attenuation. Not only are there changes in the definition of the main channel running almost north-northwest-to-south-southeast, but there are differences in the definition of subtle faults in the northeast-southwest direction.

Figure 9 shows the equivalent slices from the energy ratio coherence run on the azimuthally-limited seismic volumes as well as full-azimuth stack, as well as the equivalent stratal slice from the multiazimuth coherence. Notice the somewhat lower signal-to-noise ratio on the azimuthally-limited coherence stratal slices compared to the full-azimuth stack. The multiazimuth coherence slice captures discontinuities that are consistent across multiple azimuthally-limited volumes, weighting them by the amplitude of the data (or strength of the illumination). Note the channel and east-west faults are better delineated than on the full-azimuth coherence volume. The individual azimuthally-limited coherence volumes are shown for comparison, but for most practical purposes, the multiazimuthal coherence contains most of the detail in a single image.
Similarly, in Figures 10 and 11, we show a set of stratal slices from the same seismic volumes as in Figure 8 and 9, but at a level 22 ms lower than the horizon. Again, notice the east-west aligned fault definitions, as well as the northeast-southwest aligned en-echelon faults on the multiazimuth coherence, which stand out from all other images.

Figure 12 shows a stratal slice 78 ms below a horizon at approximately 1700ms from the (a) energy ratio coherence computed on full-azimuth seismic volume, and (b) the multiazimuth energy ratio coherence. Notice the enhanced definition of the channel features on the multiazimuth coherence as shown in the magenta and green highlighted areas. The seismic data is from the STACK trend in Oklahoma.

Multioffset coherence

Multioffset coherence can be generated in the same way as multiazimuth coherence, by simply replacing the input azimuthally-limited seismic volumes with the offset-limited seismic volumes. Generally, the reflection events at larger offsets not only lose some frequency content, but also become noisier. Appropriate mute patterns are employed on the gathers, to capture the maximum amount of signal and to ensure the best signal-to-noise ratio. Thus, despite best efforts at doing this sometimes the full-offset stacked volume may not show a high signal-to-noise ratio. While generating the multioffset coherence, care can be taken to examine the offset-limited seismic volumes for their quality and then determine which ones should be used for the generation of multioffset coherence.

Figure 13 shows stratal slices 12 ms above a horizon from a data volume from the STACK trend of Oklahoma, US. The coherence display from the full-offset coherence volume shows the
lineaments as somewhat diffused, and the four individual limited-offset coherence volumes do not yield displays that can compare with the multioffset coherence volume.

Conclusions

Coherence run on spectrally decomposed seismic volumes, especially the ones at higher frequencies within the seismic bandwidth, exhibit higher lateral resolution. Instead of running the energy ratio coherence computation on many individual volumes, we make use of multispectral coherence computation by summing the covariance matrices from individual computation windows and generating the energy ratio attribute.

The coherence attribute has traditionally been run on stacked seismic data. With more powerful workstations, we can now examine coherence attribute computations on prestack data. The energy ratio coherence computation in these cases can be done by summing the covariance matrices in the computation windows from different input volumes, and carried out in a single run.

The computation time for multispectral energy ratio is approximately three times higher than the time it takes for a conventional energy ratio coherence computation for the same input parameters.

For the datasets under study, the results from their different coherence computations exhibit encouraging results.
1. Multispectral, multiazimuth, and multi-offset/angle coherence computations exhibit higher signal-to-noise ratio and higher lateral resolution than conventional post stack coherence of full stack volumes.

2. Interpretations carried out on such coherence volumes will be less ambiguous.

3. Such coherence volumes can be used for extracting more information by way of fault probability volumes or tools like ant tracking, which are likely to provide more detail for interpretation. The imaged data however still needs to be interpreted, and that such detail extracted from the input seismic data through the methods described in this paper may improve the interpretation.

Acknowledgements

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Captions

Figure 1: A vertical slice through a 3D seismic amplitude volume from the Montney-Dawson area of northeast British Columbia. The data had been put through one pass of structure-oriented filtering and the interpreted horizons are shown in green and yellow. (*Data courtesy: TGS, Calgary*)

Figure 2: Stratal slices 36 ms above the yellow horizon shown in Figure 1 through (a) coherence volume generated on the full-offset stack, (b) multispectral coherence volume generated by using twelve selected voice component (20, 25, 30, 35, 40, 45, 50, 55, 60, 65, 70 and 75 Hz) volumes. Similar stratal slices generated along the yellow horizon though the (c) full-offset stack, and (d) multispectral coherence volume. The seismic data are from the Montney-Dawson area in British Columbia, Canada. Notice, the overall better definition of faults (indicated by yellow, cyan, and green arrows), and the paleo channels (indicated with magenta arrows) on the multispectral coherence volume shown in Figure 3b and c. (*Data courtesy: TGS, Calgary*)

Figure 3: Stratal slices 38 ms above a horizon at roughly 1400 ms through (a) coherence volume generated on the full-offset stack, (b) multispectral coherence volume generated by using twelve selected voice component (20, 25, 30, 35, 40, 45, 50, 55, 60, 65, 70 and 75 Hz) volumes, and (c)
multispectral coherence volume generated by using six selected voice component (50, 55, 60, 65, 70 and 75 Hz) volumes. The seismic data are from the Montney-Dawson area in British Columbia, Canada. Notice the overall better definition of faults (indicated with yellow, cyan and green arrows), and the paleo channels (indicated with magenta arrows) on the multispectral coherence volume shown in (b). *(Data courtesy: TGS, Calgary)*

Figure 4: A segment of a seismic section from the Montney-Dawson area in northeast British Columbia in Canada. Stratal slices have been generated between two horizons in black and are shown in red. Displays along stratal slices numbered 8, 12 and 14 are shown in Figure 5. *(Data courtesy: TGS, Calgary)*

Figure 5: Displays from the conventional (left) and multispectral (right) coherence volumes shown for stratal slices (a) 8, (b) 12 and (c) 14 marked in Figure 4. In all these displays, the definition of the channel displays is better defined and thus more easily interpretable on slices through the multispectral coherence volumes. *(Data courtesy: TGS, Calgary)*

Figure 6: Stratal slices from conventional (left) and multispectral (right) coherence volumes along (a) a horizon picked on the seismic volume at approximately 1200 ms, and (b) 68 ms below the horizon in (a). Notice the lineaments on multispectral coherence displays are more focused and continuous resulting in overall more interpretable displays. *(Data courtesy: TGS, Calgary)*

Figure 7: Segment of an inline seismic section from the STACK trend in Oklahoma. Inlines run N-S on the seismic survey as indicated in Figures 8 – 11. *(Data courtesy: TGS, Houston)*
Figure 8: Stratal slices 12 ms above a horizon at roughly 1950 ms from six azimuthally limited partial stack seismic amplitude volumes. The seismic data are from the STACK trend in Oklahoma. *(Data courtesy: TGS, Houston)*

Figure 9: Stratal slices 12 ms above a horizon at roughly 1950 ms through coherence volumes computed from the six azimuthally-limited partial stack amplitude volumes shown in Figure 5, from the full stack volume, and using a multiazimuth coherence algorithm. The definitions of the faults as well as the channels are seen much better on the multiazimuth coherence display. The seismic data are from the STACK trend in Oklahoma. *(Data courtesy: TGS, Houston)*

Figure 10: Stratal slices 22 ms below a horizon at roughly 1950 ms from ms from six azimuthally limited partial stack seismic amplitude volumes. The seismic data are from the STACK trend in Oklahoma. *(Data courtesy: TGS, Houston)*

Figure 11: Stratal slices 22 ms below a horizon at roughly 1950 ms through coherence volumes computed from the six azimuthally limited partial stack amplitude volumes shown in Figure 10, from the full stack volume, and using a multiazimuth coherence algorithm. Again, the multiazimuth coherence display stands out much better than the other displays. The seismic data are from the STACK trend in Oklahoma. *(Data courtesy: TGS, Houston)*

Figure 12: Stratal slice 78 ms below a horizon at approximately 1700ms from (a) energy ratio coherence computed on full-azimuth seismic volume, and (b) the multi-azimuth energy ratio coherence. Notice the enhanced definition of the channel features on the multi-azimuth coherence as shown in the magenta and green highlighted areas. The seismic data are from the STACK trend in Oklahoma. *(Data courtesy: TGS, Houston)*
Figure 13: Stratal slices 12 ms above a horizon at roughly 1950 ms through coherence volumes computed from the four offset-limited partially stacked volumes, from the full stack volume, and using a multioffset coherence algorithm. The definition of the faults is clearer and more focused on the multioffset coherence display when compared to the other displays. The seismic data are from the STACK trend in Oklahoma. *(Data courtesy: TGS, Houston)*
Figure 1: A vertical slice through a 3D seismic amplitude volume from the Montney-Dawson area of northeast British Columbia. The data had been put through one pass of structure-oriented filtering. (Data courtesy: TGS, Calgary)

338x190mm (230 x 230 DPI)
Figure 2

2ab

338x190mm (230 x 230 DPI)
Figure 2cd: Stratal slices 36 ms above the yellow horizon shown in Figure 1 through (a) coherence volume generated on the full-offset stack, (b) multispectral coherence volume generated by using twelve selected voice component (20, 25, 30, 35, 40, 45, 50, 55, 60, 65, 70 and 75 Hz) volumes. Similar stratal slices generated along the yellow horizon through the (c) full-offset stack, and (d) multispectral coherence volume. The seismic data are from the Montney-Dawson area in British Columbia, Canada. Notice, the overall better definition of faults (indicated by yellow, cyan, and green arrows), and the paleo channels (indicated with purple arrows) on the multispectral coherence volume shown in Figure 4. (Data courtesy: TGS, Calgary)

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Figure 3abc: Stratal slices 38 ms above a horizon at roughly 1400 ms through (a) coherence volume generated on the full-offset stack, (b) multispectral coherence volume generated by using twelve selected voice component (20, 25, 30, 35, 40, 45, 50, 55, 60, 65, 70 and 75 Hz) volumes, and (c) multispectral coherence volume generated by using six selected voice component (50, 55, 60, 65, 70 and 75 Hz) volumes. The seismic data are from the Montney-Dawson area in British Columbia, Canada. Notice the overall better definition of faults (indicated with yellow, cyan and green arrows), and the paleo channels (indicated with magenta arrows) on the multispectral coherence volume shown in (b). (Data courtesy: TGS, Calgary)

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Figure 5

338×190mm (230 × 230 DPI)
Figure 5

5b

338x190mm (230 x 230 DPI)
Figure 5c: Displays from the conventional (left) and multispectral (right) coherence volumes shown for stratal slices (a) 8, (b) 12 and (c) 14 marked in Figure 4. In all these displays, the definition of the channel displays is better defined and thus more easily interpretable. (Data courtesy: TGS, Calgary)
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DATA AND MATERIALS AVAILABILITY

Data associated with this research are available and can be obtained by contacting the corresponding author.